# PLANNING THEORY

Credit Hours: 2 (2+0)

Prerequisites: None

**Specific Objectives**

To make students aware about planning theories.

**Learning Outcomes**

After studying this course, the learners will be able to:

1. Understand the theoretical aspect of policies and planning
2. Explore how the planning theories can be applied for spatial development plan making
3. Build planning model to test the economic and regional growth for the identification of suitable location for industries, human settlement including new towns, agriculture and alike.

**Content List**

* Theory of Planning: Evolution of planning theory, ends and means in Planning
* Choice theory of Planning
* Comprehensive planning: Goal and process, advantage and disadvantage
* Incremental planning
* Mixed scanning- a science of muddling through
* Advocacy and pluralism
* Community participation and decision behavior; social planning and public participation
* Theories in Planning: economic growth models, regional growth theories, growth pole and growth center
* Locational theories for example, human settlement location, industrial location and agricultural location

**Proposed Teaching Methodology**

* Lecturing
* Demonstration

**Proposed Assessment (theory, 100%)**

**Mid Term (40%)**

* Written long/short questions, quizzes etc

**Final Term (60%)**

* Written long/short questions, quizzes etc

**Recommended Books**

1. Hall, P., and Tewdwr-Jones, M. (2011), *Urban and Regional Planning*, Routledge.
2. Greed, C. (ed.) (1999), *Social Town Planning*, Routledge.
3. John Glasson (1987), *An introduction to regional planning; Concepts, theory and practice*. Latest edition.
4. Andreas Faludi (1986) *A reader in Planning theory,* Edited/ reprint, Pergamon Press, Oxford, London.
5. Ratcliff, John (1981), *Introduction to Town and Country Planning*, London, Hutchinson.
6. Christopher Pollitt, Lew Lewis, Josephine (1979) *Public Policy In Theory And Practice: A Reader*, Hodder &Stonghton, Open University Press.
7. *Journal of RTPI*.
8. *American Journal of Planner*.